# A BGK-TYPE MODEL FOR INELASTIC BOLTZMANN EQUATIONS WITH INTERNAL ENERGY 

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#### Abstract

We introduce a model of inelastic collisions for droplets in a spray, leading to a specific Boltzmann kernel. Then, we build caricatures of this kernel of BGK type, in which the behavior of the first moments of the solution of the Boltzmann equation (that is, mass, momentum, directional temperatures, variance of the internal energy) are mimicked. The quality of these caricatures is tested numerically at the end of the paper.


## 1. INTRODUCTION

Sprays are flows in which a dispersed phase (e.g. droplets) is surrounded by a gas. Those droplets are characterized by their radius $r>0$, their position $x \in \Omega$ (domain of computation), their velocity $v \in \mathbb{R}^{3}$, and their internal energy (by unit of mass) $e>0$. [some other parameters are sometimes taken into account, like the distortion of the droplets, Cf. [AOB89, O'R81], etc.]. We restrict ourselves in this paper to so-called monodisperse sprays, where all droplets have the same radius $r>0$.

During a collision, two droplets are in contact and therefore exchange some internal energy. Moreover, the droplets being macroscopic objects, part of the kinetic energy (in the center of mass reference frame) is transformed in internal energy (that is, the collisions are inelastic).

A standard model for inelastic collisions (Cf. [BCG00, BGP04, Vil06] for example in the context of granular gases) consists in writing

$$
\begin{align*}
v^{\prime} & =\frac{v+v^{*}}{2}+\frac{1-\gamma}{4}\left(v-v^{*}\right)+\frac{1+\gamma}{4}\left|v-v^{*}\right| \sigma  \tag{1}\\
v^{\prime *} & =\frac{v+v^{*}}{2}-\frac{1-\gamma}{4}\left(v-v^{*}\right)-\frac{1+\gamma}{4}\left|v-v^{*}\right| \sigma \tag{2}
\end{align*}
$$

where $v, v^{*} \in \mathbb{R}^{3}$ are precollisional velocities, $v^{\prime}, v^{*} \in \mathbb{R}^{3}$ are postcollisional velocities, $\gamma \in[0,1]$ is the inelasticity parameter, and $\sigma$ is parametrizing the sphere $S^{2}$.

The kinetic energy lost (by unit of mass) in (1), (2) is given by

$$
\begin{equation*}
\Delta E_{c}^{\prime}=\left(1-\gamma^{2}\right) \frac{\left|v-v^{*}\right|^{2}}{8}-\frac{1-\gamma^{2}}{8}\left|v-v^{*}\right|<\sigma, v-v^{*}> \tag{3}
\end{equation*}
$$

The exchange of internal energy is then simply modelled by the equations

$$
\begin{align*}
e^{\prime} & =\frac{2-a}{2} e+\frac{a}{2} e^{*}+\frac{1}{2} \Delta E_{c}^{\prime}  \tag{4}\\
e^{\prime *} & =\frac{a}{2} e+\frac{2-a}{2} e^{*}+\frac{1}{2} \Delta E_{c}^{\prime}, \tag{5}
\end{align*}
$$

where $e, e^{*}>0$ are precollisional internal energies, $e^{\prime}, e^{\prime *}>0$ are postcollisional internal energies, and $a \in[0,1]$ is the parameter which characterizes the typical time scale of the exchange.

Note that the kinetic energy lost in (1), (2) is equally distributed between the energies $e^{\prime}$ and $e^{*}$.

In all generality, both $\gamma$ and $a$ are functions of $\left|v-v^{*}\right|$ which sometimes can be assessed (Cf. [Mat06, DMar]).

The corresponding Boltzmann operator $Q$ can be written in weak form according to the following formula (for all function $\psi$ for which the integrals make sense)

$$
\begin{gather*}
\int_{v} \int_{e} Q(f, f)(v, e) \psi(v, e) d v d e  \tag{6}\\
=\int_{v} \int_{e} \int_{v^{*}} \int_{e^{*}} \int_{\sigma} f(v, e) f\left(v^{*}, e^{*}\right)\left[\psi\left(v^{\prime}, e^{\prime}\right)-\psi(v, e)\right] r^{2} \tilde{S}\left(\left|v-v^{*}\right|\right) d v d e d v^{*} d e^{*} d \sigma, \tag{7}
\end{gather*}
$$

where

$$
\begin{equation*}
\tilde{S}(w)=w \tag{8}
\end{equation*}
$$

corresponds to the cross section of hard spheres, and $r>0$ is the radius of the droplets.
Note that by taking $\psi(v, e)=1 ; v_{i} ; \frac{|v|^{2}}{2}+e$, we obtain the conservation of mass, ( $i$ th component of the) momentum, and total (kinetic + internal) energy:

$$
\int_{v} \int_{e} Q(f, f)\left(\begin{array}{c}
1  \tag{9}\\
\left(v_{i}\right)_{i=1,2,3} \\
\frac{|v|^{2}}{2}+e
\end{array}\right) d v d e=0
$$

We also briefly indicate here the strong formulation of $Q$ [in the case of hard spheres], which makes explicit the Jacobian of the transformation $\left(v, v^{*}, e, e^{*}\right) \mapsto\left(v^{\prime}, v^{\prime *}, e^{\prime}, e^{*}\right)$, but which is not used in the sequel (cf. [Vil06] for more on the Jacobian):

$$
\begin{gather*}
Q(f, f)(v, e)= \\
\int_{v} \int_{e} \int_{\sigma}\left(J_{\left(v, v^{*}, e, e^{*}\right) \rightarrow\left({ }^{\prime} v^{\prime} v^{*}, v^{\prime}, e^{\prime} e^{*}\right)} \frac{\left.\right|^{\prime} v-^{\prime} v^{*} \mid}{\left|v-v^{*}\right|} f\left('^{\prime} v^{*}, e^{*}\right) f\left({ }^{\prime} v,^{\prime} e\right)-f\left(v^{*}, e^{*}\right) f(v, e)\right) r^{2}\left|v-v^{*}\right| d \sigma d v d e \\
=\int_{v} \int_{e} \int_{\sigma}\left(\frac{1}{\gamma^{2}} \frac{1}{1-a} f\left('^{\prime} v^{*}, e^{*}\right) f\left('^{\prime} v,^{\prime} e\right)-f\left(v^{*}, e^{*}\right) f(v, e)\right) r^{2}\left|v-v^{*}\right| d \sigma d v d e . \tag{10}
\end{gather*}
$$

The Jacobian $J$ is composed of a part $\left(\frac{1}{\gamma^{2}} \frac{\left|v-v^{*}\right|}{\left.\right|^{\prime} v v^{\prime} v^{*} \mid}\right)$ which is typical of the inelastic collision kernels ([GPV04, Vil02]), and of another part ( $\frac{1}{1-a}$ ) which comes from the exchanges of internal energies. In (10) is used the following shorthand (related to precollisional velocities, Cf. [Mat06, DMar])

$$
\begin{gather*}
\prime v=\frac{v+v^{*}}{2}-\frac{1-\gamma}{4 \gamma}\left(v-v^{*}\right)+\frac{1+\gamma}{4 \gamma}\left|v-v^{*}\right| \sigma,  \tag{11}\\
v^{*}=\frac{v+v^{*}}{2}+\frac{1-\gamma}{4 \gamma}\left(v-v^{*}\right)-\frac{1+\gamma}{4 \gamma}\left|v-v^{*}\right| \sigma,  \tag{12}\\
\prime e=\frac{2-a}{2-2 a} e-\frac{a}{2-2 a} e^{*}+\frac{1}{2} \Delta^{\prime} E_{c},  \tag{13}\\
'^{*}=-\frac{a}{2-2 a} e+\frac{2-a}{2-2 a} e^{*}+\frac{1}{2} \Delta^{\prime} E_{c},  \tag{14}\\
\Delta^{\prime} E_{c}=\frac{1-\gamma^{2}}{8 \gamma^{2}}\left|v-v^{*}\right|^{2}-\frac{1-\gamma^{2}}{8 \gamma^{2}}\left|v-v^{*}\right|\left\langle\sigma, v-v^{*}\right\rangle . \tag{15}
\end{gather*}
$$

In many instances, the Knudsen number related to the droplets in a spray is small (Cf. [Mat06, DMar]), so that the number of collisions to perform in a computation is quite high, and the treatment of $Q$ sometimes requires a large part of the time spent in the computation (up to an increase of more than $100 \%$ ).

As a consequence, one needs simplified models of collision, which lead to less expensive computations, but keep some of the main features of the original model (10) - (15).

This problem has already been studied by many authors in the case of the elastic Boltzmann operator for rarefied gases, and has led to various models, among which the BGK model (Cf. [BGK54]) and the ESS model (Cf. [LHH66]). These models have been adapted to the case of inelastic Boltzmann kernels for granular media (Cf. [AS04], [JMM00], [San03]), and to the case of Boltzmann kernels taking into account chemical reactions (Cf. [CGS07], [GK02], [MG99]).

The simplified model that we propose writes

$$
\begin{align*}
& \partial_{t} f+\nabla_{v} \cdot\left(c_{1} f\left(v-v_{a v r}\right)\right)+\partial_{e}\left(c_{2} f\right)+\partial_{e}\left(c_{3}\left(e-e_{a v r}\right) f\right)  \tag{16}\\
& \quad+\partial_{e}\left(c_{4}\left|v-v_{a v r}\right|^{4} \partial_{e} f\right)=-\nu\left(f-f_{0}\right),
\end{align*}
$$

where $v_{a v r}$ is the mean velocity

$$
\begin{equation*}
v_{a v r}=\frac{\int_{v} \int_{e} f(t, v, e) v d v d e}{\int_{v} \int_{e} f(t, v, e) d v d e} \tag{17}
\end{equation*}
$$

$e_{a v r}$ is the mean internal energy

$$
\begin{equation*}
e_{a v r}=\frac{\int_{v} \int_{e} f(t, v, e) e d e d v}{\int_{v} \int_{e} f(t, v, e) d e d v} \tag{18}
\end{equation*}
$$

$f_{0}$ is the Maxwellian function of $v$ with the same parameters as $f$

$$
\begin{equation*}
f_{0}(t, v, e)=\left(\frac{1}{2 \pi T(t)}\right)^{3 / 2} e^{-\frac{\left|v-v_{a v r}\right|^{2}}{2 T(t)}} \int_{w} f(t, w, e) d w \tag{19}
\end{equation*}
$$

and $T$ is the statistical temperature:

$$
\begin{equation*}
T(t)=\frac{1}{3} \frac{\int_{v} \int_{e} f(t, v, e)\left|v-v_{a v r}\right|^{2} d v d e}{\int_{v} \int_{e} f(t, v, e) d v d e} . \tag{20}
\end{equation*}
$$

It combines:

- a drift towards the mean velocity $\nabla_{v} \cdot\left(f\left(v-v_{\text {avr }}\right)\right)$, which enables to model the inelasticity (loss of kinetic energy) coupled with a term which ensures the conservation of total energy $\left(\partial_{e} f\right)$,
- a relaxation towards a Maxwellian distribution $-\nu\left(f-f_{0}\right)$,
- a drift towards the mean internal energy $\partial_{e}\left(\left(e-e_{\text {avr }}\right) f\right)$, which models the exchange of internal energies during collisions,
- a diffusive term $\partial_{e}\left(\left|v-v_{a v r}\right|^{4} \partial_{e} f\right)$ coming from the fact that some diffusion w.r.t. internal energy appears when part of the kinetic energy is transformed into internal energy. Note that the term $\left|v-v_{\text {avr }}\right|^{4}$ naturally appears by homogeneity if we want $c_{4}$ to be the inverse of a time.
The parameters $c_{1}, c_{2}, c_{3}, c_{4}, \nu$ are defined by

$$
\begin{gather*}
c_{1}=\frac{3 S_{1}(t)}{8 r}\left[-1+\frac{\gamma}{2}+\gamma^{2}\right](1-\alpha),  \tag{21}\\
c_{2}=-\frac{9 S_{1}(t)}{8 r}\left[-1+\frac{\gamma}{2}+\gamma^{2}\right](1-\alpha) T(t),  \tag{22}\\
c_{3}=-\frac{3 S_{3}(t)}{4 r} a(2-a)(1-\alpha),  \tag{23}\\
c_{4}=-\frac{S_{4}(t)}{32 r}\left(1-\gamma^{2}\right)^{2}(1-\alpha),  \tag{24}\\
3
\end{gather*}
$$

$$
\begin{equation*}
\nu=\frac{3 S_{1}(t)}{8 r}(1+\gamma)^{2}(1-\alpha) \tag{25}
\end{equation*}
$$

where $S_{1}, S_{3}, S_{4}$ depend on the type of collision kernel:

- In the case of Maxwell molecules (that is, when $\tilde{S}\left(\left|v-v_{*}\right|\right)=S$ is a constant in (7), we take $S_{1}(t)=S_{3}(t)=S_{4}(t)=S$;
- In the case of hard spheres (that is, when $\tilde{S}\left(\left|v-v_{*}\right|\right)=\left|v-v_{*}\right|$ ), we take

$$
\begin{gather*}
S_{1}=\sqrt{\frac{3\left(\tilde{T}_{11}^{2}+\tilde{T}_{22}^{2}+\tilde{T}_{33}^{2}\right)+2\left(\tilde{T}_{11} \tilde{T}_{22}+\tilde{T}_{22} \tilde{T}_{33}+\tilde{T}_{11} \tilde{T}_{33}\right)}{9 T^{2}} \sqrt{6 T}}  \tag{26}\\
S_{3}=\frac{4 \sqrt{T}}{\sqrt{\pi}} \\
S_{4}=\frac{32 \sqrt{T}}{5 \sqrt{\pi}}
\end{gather*}
$$

Here, the $\tilde{T}_{i i}$ are the eigenvalues of the matrix made out of the $T_{i j}$, which are the directional temperatures:

$$
\begin{equation*}
T_{i j}(t)=\frac{\int_{v} \int_{e} f\left(v_{i}-v_{i_{a v r}}\right)\left(v_{j}-v_{j_{a v r}}\right) d v d e}{\int_{v} \int_{e} f d v d e} ; \quad i, j=1 . ., 3 \tag{29}
\end{equation*}
$$

and $\alpha$ is the volume fraction of gas in the spray:

$$
\begin{equation*}
1-\alpha(t)=\int_{v} \int_{e} f(t, v, e) \frac{4}{3} \pi r^{3} d v d e \tag{30}
\end{equation*}
$$

Those coefficients are chosen in such a way that the main properties of the kernel $Q$ (conservation of mass, momentum, total energy) are satisfied, and that some typical quantities (kinetic energy, directional temperatures, variance of the internal energy) have a behavior which is as close as possible to the original kernel $Q$.

Their choice can be made in an almost completely rational way when one wishes to mimick a kernel with a cross section of Maxwell molecules type [that is, when one chooses $\tilde{S}$ as a constant function instead of (8)]. Unfortunately, in the (much more realistic) case of hard spheres (that is, when $\tilde{S}$ is given by (8)), this choice is made after some approximations which are not always valid, and other choices of coefficients are possible (we shall discuss this point in subsection 2.3).

This paper is built as follows: in Section 2 are computed (the evolution of) some moments of the density function $f$ satisfying the Boltzmann eq. $\partial_{t} f=Q(f, f)$. This computation is exact (except for the variance of internal energy) when hard spheres are replaced by Maxwell molecules, but can only be an approximation in the realistic case of hard spheres. The difficulties related to the treatment of hard spheres [that is, the link between $S_{1}, S_{3}, S_{4}$ and $\tilde{S}$ ] are discussed in subsection 2.3 .

Then, the same computation is repeated in section 3 for the simplified model (16) - (19), with arbitrary coefficients $c_{1}, ., c_{4}, \nu$. This enables the identification of the coefficients (formulas (21) to (25)).

Section 4 is devoted to the numerical simulations and comparisons between the simplified and original model. In subsection 4.1 is presented the numerical (particle Monte Carlo) scheme used to solve (16) - (19). Then, comparisons when $\tilde{S}$ is constant (case of Maxwell molecules) are shown in subsection 4.2 , while the case of hard spheres is treated in subsection 4.3. Finally, we provide in subsection 4.4 some results when $a$ and $\gamma$ depend on $\left|v-v_{*}\right|$.

## 2. Evolution of some moments of the solution of Boltzmann equation

We consider in this section a solution $f$ of the spatially homogeneous Boltzmann equation

$$
\begin{equation*}
\partial_{t} f=Q(f, f), \tag{31}
\end{equation*}
$$

where $Q$ is the kernel defined in (1) - (7) [or (10) - (15)].
We want to track the following moments in order to build our simplified model:

- The directional temperatures $T_{i j}$ defined by (29),
- The variance of the internal energy

$$
\begin{equation*}
g(t):=\frac{\int_{v} \int_{e} f\left(e-e_{a v r}\right)^{2} d v d e}{\int_{v} \int_{e} f d v d e} . \tag{32}
\end{equation*}
$$

### 2.1. Computation of some moments of the collision kernel in the case of Maxwell molecules.

In next proposition, we denote by

$$
\begin{equation*}
M_{0}=\int_{v} \int_{e} m f d v d e \tag{33}
\end{equation*}
$$

the total mass of the spray (where $m$ is the mass of a droplet).
Proposition 2.1. We consider $Q$ defined in (1) - (7), in the case when $\tilde{S}\left(\left|v-v_{*}\right|\right):=S$ is a constant function of the relative velocity (case of Maxwell molecules). The following identities hold (provided that $f$ is a smooth enough nonnegative function of $v$ )

- For $i, j=1, . ., 3, i \neq j$,

$$
\begin{equation*}
\int_{v} \int_{e} Q(f, f) m\left(v_{i}-v_{i_{a v r}}\right)\left(v_{j}-v_{j_{\text {avr }}}\right) d v d e=\frac{3 S}{r}\left[-\frac{3}{8}+\frac{\gamma}{4}\left(\frac{\gamma}{2}-1\right)\right](1-\alpha) M_{0} T_{i j}, \tag{34}
\end{equation*}
$$

- $\operatorname{For} i=1, . ., 3$,

$$
\begin{align*}
& \int_{v} \int_{e} Q(f, f) m\left(v_{i}-v_{i_{\text {avr }}}\right)^{2} d v d e=\frac{3 S}{r}\left[-\frac{3}{8}+\frac{\gamma}{4}\left(\frac{\gamma}{2}-1\right)\right](1-\alpha) M_{0} T_{i i}  \tag{35}\\
+ & \frac{3 S}{8 r}(1+\gamma)^{2}(1-\alpha) M_{0} T,
\end{align*}
$$

$$
\begin{align*}
& \int_{v} \int_{e} Q(f, f) m\left(e-e_{a v r}\right)^{2} d v d e=  \tag{36}\\
- & \frac{3 S}{2 r} a(2-a)(1-\alpha) M_{0} g \\
+ & \pi r^{2} \frac{\left(1-\gamma^{2}\right) S}{4} \iiint \int_{v, e, v^{*}, e^{*}} f f^{*} m\left(e+e^{*}-2 e_{a v r}\right)\left|v-v^{*}\right|^{2} d v d e d v_{*} d e_{*} \\
+ & \pi r^{2} \frac{\left(1-\gamma^{2}\right)^{2} S}{48} \iiint \int_{v, e, v^{*}, e^{*}} f f^{*} m\left|v-v^{*}\right|^{4} d v d e d v_{*} d e_{*} .
\end{align*}
$$

Eq. (36) can be simplified if $f$ is a tensor product (as a function of $v$ and e) in the following way:

$$
\begin{align*}
& \int_{v} \int_{e} Q(f, f) m\left(e-e_{a v r}\right)^{2} d v d e=  \tag{37}\\
- & \frac{3 S}{2 r} a(2-a)(1-\alpha) M_{0} g \\
+ & \pi r^{2} \frac{\left(1-\gamma^{2}\right)^{2} S}{48} \iiint \int_{v, e, v^{*}, e^{*}} f f^{*} m\left|v-v^{*}\right|^{4} d v d e d v_{*} d e_{*} .
\end{align*}
$$

It can even be further simplified when moreover $f$ is an (isotropic) Gaussian function of $v$ :

$$
\begin{equation*}
f(v, e)=\left(\int_{v} f(w, e) d w\right) \frac{1}{(2 \pi T)^{3 / 2}} \exp \left(-\frac{\left|v-v_{a v r}\right|^{2}}{2 T}\right) \tag{38}
\end{equation*}
$$

In that case, we end up with

$$
\begin{align*}
& \int_{v} \int_{e} Q(f, f) m\left(e-e_{a v r}\right)^{2} d v d e=  \tag{39}\\
- & \frac{3 S}{2 r} a(2-a)(1-\alpha) M_{0} g+\frac{15 S}{16 r}\left(1-\gamma^{2}\right)^{2}(1-\alpha) M_{0} T^{2}
\end{align*}
$$

## Proof of Proposition 2.1:

We use formula (7) for $\psi=m\left(v_{i}-v_{i_{a v r}}\right)\left(v_{j}-v_{j_{\text {avr }}}\right)$. Remembering that

$$
\begin{equation*}
v^{\prime}=\frac{v+v^{*}}{2}+\frac{1-\gamma}{4}\left(v-v^{*}\right)+\frac{1+\gamma}{4}\left|v-v^{*}\right| \sigma, \tag{40}
\end{equation*}
$$

we see that for $i \neq j$,

$$
\begin{align*}
\psi^{\prime}= & m\left(\frac{v_{i}+v_{i}^{*}}{2}-v_{i_{a v r}}+\frac{1-\gamma}{4}\left(v_{i}-v_{i}^{*}\right)+\frac{1+\gamma}{4}\left|v-v^{*}\right| \sigma_{i}\right) \\
& \times\left(\frac{v_{j}+v_{j}^{*}}{2}-v_{j_{a v r}}+\frac{1-\gamma}{4}\left(v_{j}-v_{j}^{*}\right)+\frac{1+\gamma}{4}\left|v-v^{*}\right| \sigma_{j}\right) . \tag{41}
\end{align*}
$$

Using the symmetry relations

$$
\begin{equation*}
\forall i \neq j, \quad \int_{\sigma \in \mathbb{S}^{2}} \sigma_{i} d \sigma=0, \quad \int_{\sigma \in \mathbb{S}^{2}} \sigma_{i} \sigma_{j} d \sigma=0 \tag{42}
\end{equation*}
$$

we end up with

$$
\begin{align*}
\frac{1}{4 \pi} \int_{\sigma \in \mathbb{S}^{2}} \psi^{\prime} d \sigma= & m\left[\left(\frac{v_{i}+v_{i}^{*}}{2}-v_{i_{a v r}}\right)\left(\frac{v_{j}+v_{j}^{*}}{2}-v_{j_{a v r}}\right)+\left(\frac{v_{i}+v_{i}^{*}}{2}-v_{i_{a v r}}\right) \frac{1-\gamma}{4}\left(v_{j}-v_{j}^{*}\right)\right. \\
& \left.+\frac{1-\gamma}{4}\left(v_{i}-v_{i}^{*}\right)\left(\frac{v_{j}+v_{j}^{*}}{2}-v_{j_{a v r}}\right)+\left(\frac{1-\gamma}{4}\right)^{2}\left(v_{i}-v_{i}^{*}\right)\left(v_{j}-v_{j}^{*}\right)\right] \tag{43}
\end{align*}
$$

and

$$
\begin{aligned}
\frac{1}{4 \pi} \int_{\sigma \in \mathbb{S}^{2}}\left(\psi^{\prime}-\psi\right) d \sigma= & m\left[\frac{-7}{16}-\frac{3 \gamma}{8}+\frac{\gamma^{2}}{16}\right]\left(v_{i}-v_{i a v r}\right)\left(v_{j}-v_{j_{a v r}}\right) \\
& +m\left[\frac{1}{16}+\frac{\gamma}{8}+\frac{\gamma^{2}}{16}\right]\left(v_{i}^{*}-v_{i a v r}\right)\left(v_{j}^{*}-v_{j_{a v r}}\right) \\
& +A_{\perp\left(v, v^{*}\right)}\left(v_{i}-v_{i_{\text {moy }}}\right)\left(v_{j}^{*}-v_{j_{\text {moy }}}\right)+B_{\perp\left(v, v^{*}\right)}\left(v_{j}-v_{j_{m o y}}\right)\left(v_{i}^{*}-v_{i_{m o y}}\right)
\end{aligned}
$$

for some quantities $A_{\perp\left(v, v^{*}\right)}$ and $B_{\perp\left(v, v^{*}\right)}$ that will disappear when the integration over $d v d v^{*}$ is performed.

Using the weak formulation (7),

$$
\begin{align*}
& \int_{v} \int_{e} Q(f, f) m\left(v_{i}-v_{i_{a v r}}\right)\left(v_{j}-v_{j_{a v r}}\right) d v d e  \tag{45}\\
= & 4 \pi S\left[\frac{-3}{8}-\frac{\gamma}{4}+\frac{\gamma^{2}}{8}\right] \iiint \int_{v, e, v^{*}, e^{*}} f f^{*} m\left(v_{i}-v_{i_{a v r}}\right)\left(v_{j}-v_{j_{a u r}}\right) r^{2} d v d e d v^{*} d e^{*} \\
= & 4 \pi S\left[\frac{-3}{8}-\frac{\gamma}{4}+\frac{\gamma^{2}}{8}\right](\underbrace{\int_{v} \int_{e} f m\left(v_{i}-v_{i_{a v r} r}\right)\left(v_{j}-v_{j_{a v r}}\right) d v d e}_{T_{i j} M_{0}})(\underbrace{\left.\int_{v^{*}}^{\int_{e^{*}} f^{*} r^{2} d v^{*} d e^{*}}\right)}_{\frac{3}{4 \pi r}(1-\alpha)} \\
= & \frac{3 S}{r}\left[\frac{-3}{8}+\frac{\gamma}{4}\left(\frac{\gamma}{2}-1\right)\right](1-\alpha) M_{0} T_{i j} .
\end{align*}
$$

We obtain therefore formula (34).

We now turn to the case when $i=j$, and take consequently $\psi=m\left(v_{i}-v_{i_{\text {avr }}}\right)^{2}$. The computation runs thus:

$$
\begin{align*}
\frac{1}{4 \pi} \int_{\sigma \in \mathbb{S}^{2}}\left(\psi^{\prime}-\psi\right) d \sigma & =m\left(v_{i}-v_{i_{\text {aur }}}\right)^{2}\left[\frac{-7}{16}-\frac{3 \gamma}{8}+\frac{\gamma^{2}}{16}\right]  \tag{46}\\
& +m\left(v_{i}^{*}-v_{i_{\text {aur }}}\right)^{2}\left[\frac{1}{16}+\frac{\gamma}{8}+\frac{\gamma^{2}}{16}\right]+m \frac{(1+\gamma)^{2}}{16}\left|v-v^{*}\right|^{2} \frac{1}{3} \\
& +C_{\perp\left(v, v^{*}\right)}\left(v_{i}-v_{i_{\text {moy }}}\right)\left(v_{i}^{*}-v_{i_{\text {moy }}}\right),
\end{align*}
$$

where the last term will vanish after integration over $d v d v^{*}$. Then,

$$
\begin{align*}
& \iiint \int_{v, e, v^{*}, e^{*}} f f^{*} m \frac{(1+\gamma)^{2}}{16}\left|v-v^{*}\right|^{2} \frac{4 \pi}{3} r^{2} \tilde{S}\left(\left|v-v^{*}\right|\right) d v d e d v^{*} d e^{*}  \tag{47}\\
= & \frac{3 S}{8 r}(1+\gamma)^{2} M_{0}(1-\alpha) T .
\end{align*}
$$

Recalling the computation leading to formula (34), we end up with formula (35).

Next computation is related to the moment $g$ defined in (32). We observe that

$$
\begin{align*}
& \frac{1}{4 \pi} \int_{\sigma}\left[\left(e^{\prime *}\right)^{2}+\left(e^{\prime}\right)^{2}-\left(e^{*}\right)^{2}-e^{2}\right] d \sigma  \tag{48}\\
= & -\frac{a(2-a)}{2}\left(e-e^{*}\right)^{2}+\left(1-\gamma^{2}\right) \frac{\left|v-v^{*}\right|^{2}}{8}\left(e+e^{*}\right) \\
+ & \frac{1}{128}\left(1-\gamma^{2}\right)^{2}\left|v-v^{*}\right|^{4}+\frac{1}{128}\left(1-\gamma^{2}\right)^{2}\left|v-v^{*}\right|^{2} \frac{1}{4 \pi} \int_{\sigma}\left(\left\langle\sigma \mid v-v^{*}\right\rangle\right)^{2} d \sigma,
\end{align*}
$$

so that

$$
\begin{align*}
& J:= \iint_{v, e} Q(f, f) m\left(e-e_{a v r}\right)^{2} d v d e  \tag{49}\\
&= \frac{1}{2} \iiint \int_{v, e, v^{*}, e^{*}} \int_{\sigma} f f^{*} m[\underbrace{-\frac{a(2-a)}{2}\left(e-e^{*}\right)^{2}}_{A}+\underbrace{\left(1-\gamma^{2}\right) \frac{\left|v-v^{*}\right|^{2}}{8}\left(e+e^{*}\right)}_{C} \\
&+\underbrace{\frac{1}{128}\left(1-\gamma^{2}\right)^{2}\left|v-v^{*}\right|^{4}}_{B} \\
& \underbrace{\frac{1}{128}\left(1-\gamma^{2}\right)^{2}\left|v-v^{*}\right|^{2}\left(<\sigma \mid v-v^{*}>\right)^{2}}_{E} \\
&\underbrace{-e_{a v r}\left(1-\gamma^{2}\right) \frac{\left|v-v^{*}\right|^{2}}{4}}_{D}] r^{2} \tilde{S}\left(\left|v-v^{*}\right|\right) d v d e d v^{*} d e^{*} d \sigma .
\end{align*}
$$

Some of the terms appearing in this formula can be computed:

- For $A$ :

$$
\begin{equation*}
\iiint \int_{v, e, v^{*}, e^{*}} \int_{\sigma} f f^{*} m A r^{2} \tilde{S}\left(\left|v-v^{*}\right|\right) d v d e d v^{*} d e^{*} d \sigma=-\frac{3 S}{r} a(2-a)(1-\alpha) M_{0} g . \tag{50}
\end{equation*}
$$

- We deal with the terms $B$ and $E$ together, since they both lead to the appearance of a "cross moment".

$$
\begin{align*}
& \iiint \int_{v, e, v^{*}, e^{*}} \int_{\sigma} f f^{*} m(B+E) r^{2} \tilde{S}\left(\left|v-v^{*}\right|\right) d v d e d v^{*} d e^{*} d \sigma  \tag{51}\\
= & \pi r^{2} S \frac{1-\gamma^{2}}{2} \iiint \int_{v, e, v^{*}, e^{*}} f f^{*} m\left(e+e^{*}-2 e_{a v r}\right)\left|v-v^{*}\right|^{2} d v d e d v^{*} d e^{*} .
\end{align*}
$$

In the case when the distribution w.r.t. energy is independent of the distribution w.r.t. velocity (i.-e. when $f$ is a tensor product), we see that

$$
\begin{equation*}
\iiint \int_{v, e, v^{*}, e^{*}} \int_{\sigma} f f^{*} m(B+E) r^{2} \tilde{S}\left(\left|v-v^{*}\right|\right) d v d e d v^{*} d e^{*} d \sigma=0 . \tag{52}
\end{equation*}
$$

- We now focus on the terms $C$ and $D$. After integration w.r.t. $\sigma$, we obtain

$$
\begin{align*}
J_{2} & :=\iiint \int_{v, e, v^{*}, e^{*}} \int_{\sigma} f f^{*} m(C+D) r^{2} \tilde{S}\left(\left|v-v^{*}\right|\right) d v d e d v^{*} d e^{*} d \sigma  \tag{53}\\
& =\frac{\left(1-\gamma^{2}\right)^{2}}{24} r^{2} S \pi m \iiint \int_{v, e, v^{*}, e^{*}} f f^{*}\left|v-v^{*}\right|^{4} d v d e d v^{*} d e^{*} .
\end{align*}
$$

Then, if $f$ is an (isotropic) gaussian function of $v$ (that is, (38) holds), one gets

$$
\begin{equation*}
\iiint \int_{v, e, v^{*}, e^{*}} f f^{*}\left|v-v^{*}\right|^{4} d v d v^{*} d e d e^{*}=60 T^{2}\left(\int_{v} \int_{e} f d v d e\right)^{2} . \tag{5}
\end{equation*}
$$

All in all, we end up with (36), (37) and (39).
2.2. Evolution of the moments of the Boltzmann equation in the case of Maxwell molecules. We now consider a (smooth) solution of eq. (31).

Using (34) and (35), we get an equation satisfied by the directional temperature $T_{i j}$, for $i, j=$ $1, ., 3, i \neq j$ :

$$
\begin{equation*}
\frac{d}{d t} T_{i j}(t)=\frac{3 S}{r}\left[\frac{-3}{8}+\frac{\gamma}{4}\left(\frac{\gamma}{2}-1\right)\right](1-\alpha) T_{i j}(t), \tag{55}
\end{equation*}
$$

and by the directional temperature $T_{i i}$, for $i=1, . ., 3$ :

$$
\begin{equation*}
\frac{d}{d t} T_{i i}(t)=\frac{3 S}{r}\left[\frac{-3}{8}+\frac{\gamma}{4}\left(\frac{\gamma}{2}-1\right)\right](1-\alpha) T_{i i}(t)+\frac{3 S}{8 r}(1+\gamma)^{2}(1-\alpha) T(t) . \tag{56}
\end{equation*}
$$

Note that the evolution of the temperature $T(t)$ can be recovered by adding (56) for $i=1,2,3$ :

$$
\begin{equation*}
\frac{d}{d t} T(t)=\frac{3 S}{4 r}\left(\gamma^{2}-1\right)(1-\alpha) T(t) \tag{57}
\end{equation*}
$$

It is not possible to obtain a closed equation for $g$ without using some approximation. We shall use formula (39), which in principle only holds for functions which are tensor products, and which moreover are Gaussian functions of $v$.

We end up with the following approximate equation:

$$
\begin{equation*}
\frac{d}{d t} g(t) \approx-\frac{3 S}{2 r} a(2-a)(1-\alpha) g(t)+\frac{15}{16 r}\left(1-\gamma^{2}\right)^{2}(1-\alpha) S T^{2} . \tag{58}
\end{equation*}
$$

The quality of the approximation leading to (58) will be tested at the numerical level in subsection 4.2 (Fig. 13).

### 2.3. Evolution of the moments of the Boltzmann equation in the case of hard spheres.

In the case of hard spheres (that is, when $\tilde{S}$ satisfies (8)), no closed equations can be written down for the directional temperature $T_{i j}$. We use therefore approximate equations.

Our choice is the following: we write

$$
\begin{align*}
& \quad \frac{d}{d t} T_{i j}(t) \approx \frac{3 S_{1}(t)}{r}\left[\frac{-3}{8}+\frac{\gamma}{4}\left(\frac{\gamma}{2}-1\right)\right](1-\alpha) T_{i j}(t), \quad i, j=1 . .3, i \neq j,  \tag{59}\\
& \left(60 \frac{d}{d t} T_{i i}(t) \approx \frac{3 S_{1}(t)}{r}\left[\frac{-3}{8}+\frac{\gamma}{4}\left(\frac{\gamma}{2}-1\right)\right](1-\alpha) T_{i i}(t) \quad+\frac{3 S_{1}(t)}{8 r}(1+\gamma)^{2}(1-\alpha) T(t), \quad i=1, . .3,\right.
\end{align*}
$$

that is, a set of equations identical to those which are written in the case of Maxwell molecules, except that the constant $S$ is replaced by a function $S_{1}(t)$ of the time $t$, which approximates $\left|v-v_{*}\right|$ at time $t$.
Many different choices are possible for $S_{1}$, our proposition is formula (26). This corresponds to taking for $f$ an anisotropic gaussian function of $v$, that is, in a diagonal basis for the matrix of directional temperatures $\left(\right.$ where $v=\left(\tilde{v}_{1}, \tilde{v}_{2}, \tilde{v}_{3}\right)$ and $\left.v_{\text {avr }}=\left(\tilde{v}_{1_{\text {avr }}}, \tilde{v}_{2_{\text {avr }}}, \tilde{v}_{3_{\text {avr }}}\right):\right)$

$$
\begin{equation*}
f=\left(\int_{w} f d w\right) \frac{1}{(2 \pi)^{3 / 2} \sqrt{\tilde{T}_{11} \tilde{T}_{22} \tilde{T}_{33}}} e^{-\frac{\left(\tilde{v}_{1}-\tilde{v}_{1 a v r}\right)^{2}}{2 \tilde{T}_{11}}} e^{-\frac{\left(\tilde{v}_{2}-\tilde{v}_{2 a v r}\right)^{2}}{2 \tilde{T}_{22}}} e^{-\frac{\left(\tilde{v}_{3}-\tilde{v}_{3 a v}\right)^{2}}{2 \tilde{T}_{33}}}, \tag{61}
\end{equation*}
$$

in the formula

$$
\begin{equation*}
\left(\frac{\int_{v} \int_{e} \int_{v^{*}} \int_{e^{*}} f f^{*}\left|v-v^{*}\right|^{4} d v d v^{*} d e d e^{*}}{\int_{v} \int_{e} \int_{v^{*}} \int_{e^{*}} f f^{*}\left|v-v^{*}\right|^{2} d v d v^{*} d e d e^{*}}\right)^{1 / 2}, \tag{62}
\end{equation*}
$$

considered as an approximation of

$$
\begin{equation*}
\frac{\int_{v} \int_{e} \int_{v^{*}} \int_{e^{*}} f f^{*}\left|v-v^{*}\right|^{3} d v d v^{*} d e d e^{*}}{\int_{v} \int_{e} \int_{v^{*}} \int_{e^{*}} f f^{*}\left|v-v^{*}\right|^{2} d v d v^{*} d e d e^{*}} \tag{63}
\end{equation*}
$$

We now discuss the relevance of our approximation: we compare the results obtained with the original Boltzmann equation (with hard spheres) and different approximate models of the cross
section with the simplified BGK type model. We try three differents approximations of the cross section, the first one consists in computing $\left|v-v^{*}\right|$ as a quadratic mean, that is:

$$
\begin{equation*}
\left|v-v^{*}\right| \approx \sqrt{\frac{\int_{v} \int_{e} \int_{v^{*}} \int_{e^{*}} f f^{*}\left|v-v^{*}\right|^{2} d v d e d v^{*} d e^{*}}{\int_{v} \int_{e} \int_{v^{*}} \int_{e^{*}} f f^{*} d v d e d v^{*} d e^{*}}} \tag{64}
\end{equation*}
$$

which amounts to replace $\left|v-v^{*}\right|$ by $\sqrt{6 T(t)}$. The second choice consists in replacing the anisotropic gaussian function by an isotropic one. This leads to the formula $\left|v-v^{*}\right| \approx \sqrt{\frac{15}{9}} \sqrt{6 T(t)}$. The last one corresponds to formula (26).

The numerical results are presented in Fig. 1 and show that formula (64) is much less efficient than the other ones. The gain obtained by using an anisotropic gaussian function instead of an isotropic one is slight (and does not necessarily justify the use of a complex formula like (26)).

We now propose an approximate equation for the variance $g$ of the internal energy. We write

$$
\begin{equation*}
\frac{d}{d t} g(t) \approx-\frac{3}{2 r} a(2-a)(1-\alpha) S_{3}(t) g(t)+\frac{15}{16 r}\left(1-\gamma^{2}\right)^{2}(1-\alpha) S_{4}(t) T^{2}, \tag{65}
\end{equation*}
$$

that is, an equation identical to the one written in the case of Maxwell molecules, except that the constant $S$ is replaced by functions $S_{3}(t)$ and $S_{4}(t)$ of the time $t$, which approximate $\left|v-v_{*}\right|$ at time $t$.

Here, we propose the simplest formula for $S_{3}$, that is, we consider (27), which corresponds to taking $S_{3}$ as the quantity

$$
\begin{equation*}
\left|v-v^{*}\right| \approx \frac{\iiint \int_{v, e, v^{*}, e^{*}} f f^{*}\left|v-v^{*}\right| d v d v^{*} d e d e^{*}}{\iiint \int_{v, e, v^{*}, e^{*}} f f^{*} d v d v^{*} d e d e^{*}} \tag{66}
\end{equation*}
$$

when $f$ is an (isotropic) Gaussian function of $v$ (that is, formula (38) holds).
We now discuss the quality of this approximation. We compare in Fig. 4 the results obtained with the original Boltzmann equation and the results with our simplified kinetic model with two different approximations for $S_{3}(t)$ : the one given by (27), and the other using $\left|v-v_{*}\right| \approx \sqrt{6 T}$ (that is, (64)). We use a numerical simulation of the elastic case $(\gamma=1)$ since in that case, the positive term in (65) disappears, so that only the approximation involving $S_{3}(t)$ counts.

Fig. 4 shows that the approximation using (27) is much more efficient than the one using (64).
We take for $S_{4}$ the formula $S_{4}=\frac{32 T^{1 / 2}}{5 \sqrt{\pi}}$. This corresponds to computing $S_{4}(t)$ as the value of the following ratio:

$$
\begin{equation*}
S_{4}(t) \approx \frac{\int_{v} \int_{e} \int_{v^{*}} \int_{e^{*}} f f^{*}\left|v-v^{*}\right|^{5} d v d v^{*} d e d e^{*}}{\int_{v} \int_{e} \int_{v^{*}} \int_{e^{*}} f f^{*}\left|v-v^{*}\right|^{4} d v d v^{*} d e d e^{*}}, \tag{67}
\end{equation*}
$$

when $f$ is given by (38). The formula $S_{4}=\frac{32 T^{1 / 2}}{5 \sqrt{\pi}}$ is a consequence of

$$
\begin{equation*}
\iiint \int_{v, e, v^{*}, e^{*}} f f^{*} m\left|v-v^{*}\right|^{5} d v d v^{*} d e d e^{*}=\frac{384 T^{5 / 2}}{\sqrt{\pi}} m\left(\int_{v} \int_{e} f d v d e\right)^{2}, \tag{68}
\end{equation*}
$$

and (54) [with $f$ given by (38].
This yields for $J_{2}$ in eq. (53) (replacing $S_{4}(t)$ by its value) the following formula

$$
\begin{equation*}
J_{2}=\frac{12}{r \sqrt{\pi}}\left(1-\gamma^{2}\right)^{2}(1-\alpha) M_{0} T^{5 / 2} \tag{69}
\end{equation*}
$$

and so

$$
\begin{equation*}
\frac{d}{d t} g(t) \approx-\frac{3}{2 r} a(2-a)(1-\alpha) S_{3} g(t)+\frac{6}{r \sqrt{\pi}}\left(1-\gamma^{2}\right)^{2}(1-\alpha) T^{5 / 2} \tag{70}
\end{equation*}
$$

The interest of using formula (28) instead of $\sqrt{6 T}$ (that is, (64)) can be seen on the numerical simulation yielding Fig. 5. There, we have set the internal energy exchange parameter at 0 , so that the negative part of (70) vanishes, and only the quality of the approximation of $S_{4}$ is tested.

## 3. Establishment of the simplified model

3.1. Evolution of the moments of the simplified model with arbitrary coefficients. We introduce here the simplified model [which hopefully mimicks the behavior of (10) - (11)], with arbitrary coefficients $c_{1}, \ldots, c_{4}, \nu$ :

$$
\begin{align*}
& \partial_{t} f+\nabla_{v} \cdot\left(c_{1} f\left(v-v_{a v r}\right)\right)+\partial_{e}\left(c_{2} f+c_{3}\left(e-e_{a v r}\right) f+c_{4}\left|v-v_{a v r}\right|^{4} \partial_{e} f\right)  \tag{71}\\
= & -\nu\left(f-f_{0}\right)
\end{align*}
$$

where $v_{a v r}, e_{a v r}$, and $f_{0}$ are defined by (17), (18) and (19).
It is possible to compute explicitly the evolution of some moments of the solution of eq. (71). Those computations are summarized in the following
Proposition 3.1. We assume that $c_{1}, . ., c_{4}, \nu \geq 0$ do not depend on $v, e$ (they can depend on $T$ and $t$ ). Then the (smooth) solutions of eq. (71) satisfy the following properties:

- Conservation of mass and momentum:

$$
\begin{equation*}
\partial_{t} \int_{v} \int_{e} f\binom{1}{v} d v d e=0 \tag{72}
\end{equation*}
$$

- Evolution of the total energy:

$$
\begin{equation*}
\partial_{t} \int_{v} \int_{e} m f\left(\frac{|v|^{2}}{2}+e\right) d v d e=\left[3 c_{1} T+c_{2}\right] M_{0} \tag{73}
\end{equation*}
$$

- Evolution of the directional temperatures:

$$
\begin{gather*}
\forall i, j=1, \ldots, 3, i \neq j, \quad \partial_{t} T_{i j}=\left(2 c_{1}-\nu\right) T_{i j},  \tag{74}\\
\forall i=1, . ., 3, \quad \partial_{t} T_{i i}=\left(2 c_{1}-\nu\right) T_{i i}+\nu T \tag{75}
\end{gather*}
$$

- Evolution of the variance of the internal energy:

$$
\begin{equation*}
\partial_{t} g=2 c_{3} g-\frac{2 c_{4}}{M_{0}} \int_{v} \int_{e} f m\left|v-v_{a v r}\right|^{4} d v d e \tag{76}
\end{equation*}
$$

Proof of Proposition 3.1: The property of conservation (72) is directly obtained thanks to the definition of $v_{\text {aur }}$.

We then compute the evolution of the kinetic energy. The terms in $\partial_{e}$ obviously do not contribute to its evolution. Moreover,

$$
\begin{gather*}
\int_{v} \int_{e} \nabla_{v} \cdot\left(c_{1} f\left(v-v_{a v r}\right)\right) m \frac{|v|^{2}}{2} d v d e=-3 c_{1} M_{0} T,  \tag{77}\\
\int_{v} e^{-\frac{\left|v-v_{a v r}\right|^{2}}{2 T}} m \frac{|v|^{2}}{2} d v=\frac{3}{2} m(2 \pi)^{3 / 2} T^{5 / 2}+\frac{1}{2} m(2 \pi T)^{3 / 2}\left|v_{a v r}\right|^{2}, \tag{78}
\end{gather*}
$$

and thus :

$$
\begin{gather*}
\int_{v} \int_{e} f_{0}(t, v, e) m \frac{|v|^{2}}{2} d v d e=M_{0}\left[\frac{3}{2} T+\frac{1}{2}\left|v_{a v r}\right|^{2}\right] \\
=\int_{v} \int_{e} f m \frac{|v|^{2}}{2} d v d e:=E_{c} . \tag{79}
\end{gather*}
$$

The evolution of the internal energy can easily be computed since the only term giving a non-zero contribution is $\partial_{e}\left(c_{2} f\right)$. We get

$$
\begin{equation*}
\int_{v} \int_{e} m e \partial_{e}\left(c_{2} f\right) d e d v=-c_{2} M_{0} \tag{80}
\end{equation*}
$$

Collecting all those terms, we end up with eq. (73).
Next, we examine the evolution of directional temperatures for solutions of (71). As in the computation of the evolution of the total energy, the terms in $\partial_{e}$ obviously give no contributions at this level.

For the contributions related to $c_{1} f\left(v-v_{\text {avr }}\right)$, we get the following formulas: For $k \neq l$,

$$
\begin{gather*}
\iint_{v, e} \nabla_{v} \cdot\left(c_{1} f\left(v-v_{\text {avr }}\right)\right) m\left(v_{k}-v_{k_{\text {avr }}}\right)\left(v_{l}-v_{l_{\text {avr }}}\right) d v d e= \\
-c_{1} \sum_{i=1, \ldots, 3} \iint_{v, e} f m\left[\left(v_{i}-v_{i_{\text {aur }}}\right) \partial_{v_{i}}\left(\left(v_{k}-v_{k_{\text {avr }}}\right)\left(v_{l}-v_{l_{\text {avr }}}\right)\right)\right] d v d e \\
=-c_{1} \sum_{i=1, \ldots, 3} \iint_{v, e} f m\left(v_{i}-v_{i_{\text {aur }}}\right)\left[\delta_{i=k}\left(v_{l}-v_{l_{\text {avr }}}\right)+\delta_{i=l}\left(v_{k}-v_{k_{\text {avr }}}\right)\right] d v d e \\
=-2 c_{1} \iint_{v, e} f m\left(v_{l}-v_{l_{\text {avr }}}\right)\left(v_{k}-v_{k_{\text {avr }}}\right) d v d e \\
=-2 c_{1} M_{0} T_{k l}(t) ; \tag{81}
\end{gather*}
$$

For $k=l$,

$$
\begin{equation*}
\int_{v} \int_{e} \nabla_{v} \cdot\left(c_{1} f\left(v-v_{a v r}\right)\right) m\left(v_{k}-v_{k_{a v r}}\right)^{2} d v d e=-2 c_{1} M_{0} T_{k k}(t) \tag{82}
\end{equation*}
$$

Finally, for the contribution related to $-\nu\left(f-f_{0}\right)$, we get when $k \neq l$ :

$$
\begin{equation*}
\int_{v} \int_{e}-\nu\left(f-f_{0}\right) m\left(v_{k}-v_{k_{a v r}}\right)\left(v_{l}-v_{l a v r}\right) d v d e=-\nu M_{0} T_{k l}(t), \tag{83}
\end{equation*}
$$

and when $k=l$,

$$
\begin{equation*}
\int_{v} \int_{e}-\nu\left(f-f_{0}\right) m\left(v_{k}-v_{k_{a v r}}\right)^{2} d v d e=-\nu M_{0} T_{k k}(t)+\nu M_{0} T(t) . \tag{84}
\end{equation*}
$$

Collecting all the terms, we obtain eq. (74) and eq. (75).
We finally examine the contributions of the various terms on the evolution of $g$. Obviously, the terms in $\nabla_{v}$ do not contribute to the evolution of $g$, and the same holds for $\partial_{e}\left(c_{2} f\right)$.

Then,

$$
\begin{gather*}
\int_{v} \int_{e} \partial_{e}\left(c_{3}\left(e-e_{a v r}\right) f\right) m\left(e-e_{a v r}\right)^{2} d v d e=-2 c_{3} M_{0} g(t)  \tag{85}\\
\int_{v} \int_{e} \partial_{e}\left(c_{4}\left|v-v_{a v r}\right|^{4} \partial_{e} f\right) m\left(e-e_{a v r}\right)^{2} d v d e=2 c_{4} \iint_{v, e} f m\left|v-v_{a v r}\right|^{4} d v d e \tag{86}
\end{gather*}
$$

and

$$
\begin{align*}
-\nu \int_{v} \int_{e} f m\left(e-e_{a v r}\right)^{2} d v d e & =-\nu M_{0} g(t)  \tag{87}\\
\nu \int_{v} \int_{e} f_{0} m\left(e-e_{a v r}\right)^{2} d v d e & =\nu M_{0} g(t) \tag{88}
\end{align*}
$$

Finally, the evolution of $g$ is given by eq. (76).
This ends the proof of Prop. 3.1.
3.2. Computation of the coefficients; case of Maxwell molecules. We now write down the constraints on the parameters which enable to identify the behavior of the moments (total energy, $g$ and $T_{i j}$ ) for the simplified model and for the original model, in the case of Maxwell molecules (that is, when $\tilde{S}\left(\left|v-v_{*}\right|\right)=S$ ).

In order to recover the conservation of total energy which held in the original model, one needs to ensure (according to (73)) that

$$
\begin{equation*}
c_{2}=-3 c_{1} T . \tag{89}
\end{equation*}
$$

In order to mimick the behavior of the directional temperatures when $f$ satisfies the original model, we write the following constraints (corresponding to the cases $i \neq j$ and $i=j$ respectively):

$$
\begin{align*}
2 c_{1}-\nu & =\frac{3 S}{r}\left[-\frac{3}{8}+\frac{\gamma}{4}\left(\frac{\gamma}{2}-1\right)\right](1-\alpha),  \tag{90}\\
\nu & =\frac{3 S}{8 r}(1+\gamma)^{2}(1-\alpha) . \tag{91}
\end{align*}
$$

Finally, we wish to mimick the behavior of $g$. This first leads to

$$
\begin{equation*}
c_{3}=-\frac{3}{4 r} a(2-a)(1-\alpha) S . \tag{92}
\end{equation*}
$$

It remains to perform the computation of $\iint_{v, e} f m\left|v-v_{a v r}\right|^{4} d v d e$. This is not possible in general, and we retain as an approximate result what is obtained when $f$ is assumed to be an (isotropic) Gaussian w.r.t. $v$ (that is, $f$ is given by formula (38)). In this situation, one is led to

$$
\begin{equation*}
\iint_{v, e} f m\left|v-v_{a v r}\right|^{4} d v d e=15 M_{0} T^{2} . \tag{93}
\end{equation*}
$$

Then, the identification with the (approximate) ode (58) satisfied by $g(t)$ when $f$ is solution of the Boltzmann equation with Maxwell molecules leads to:

$$
\begin{equation*}
c_{4}=-\frac{1}{32 r}\left(1-\gamma^{2}\right)^{2}(1-\alpha) S . \tag{94}
\end{equation*}
$$

Collecting all those identities, we get the equations (21) - (25) for the parameters of the model described in the introduction (with $S_{1}(t)=S_{3}(t)=S_{4}(t)=S$ ).
3.3. Computation of the coefficients; case of hard spheres. In this subsection, we write down the constraints on the parameters which enable to identify the behavior of the moments (total energy, $g$ and $T_{i j}$ ) for the simplified model and for the original model, in the case of hard spheres (that is, $\left.\tilde{S}\left(\left|v-v_{*}\right|\right)=\left|v-v_{*}\right|\right)$.

The conservation of total energy still leads to eq. (89). Then, it is easy to see that (90) - (92), (94) become

$$
\begin{align*}
2 c_{1}-\nu & =\frac{3 S_{1}}{r}\left[-\frac{3}{8}+\frac{\gamma}{4}\left(\frac{\gamma}{2}-1\right)\right](1-\alpha),  \tag{95}\\
\nu & =\frac{3 S_{1}}{8 r}(1+\gamma)^{2}(1-\alpha),  \tag{96}\\
c_{3} & =-\frac{3}{4 r} a(2-a)(1-\alpha) S_{3},  \tag{97}\\
c_{4} & =-\frac{1}{32 r}\left(1-\gamma^{2}\right)^{2}(1-\alpha) S_{4}, \tag{98}
\end{align*}
$$

where $S_{1}, S_{3}$ and $S_{4}$ are given by (26), (27) and (28). In the last equation, the same assumptions on $\int_{v} \int_{e} f m\left|v-v_{a v r}\right|^{4} d v d e$ has been performed as in the case of Maxwell molecules. We end up again with the equations (21) - (25) for the parameters of the model described in the introduction.

We have thus obtained our simplified model in the case of Maxwell molecules as well as in the case of hard spheres.
3.4. Extension of the model when $a, \gamma$ depend on $\left|v-v_{*}\right|$. We now briefly explain how to extend our analysis when the kernel $Q$ (with hard spheres cross section) defined in (10) - (15) includes inelasticity and energy exchange parameters $a$ and $\gamma$ which depend on $\left|v-v_{*}\right|$ instead of being absolute constants, that is, $a:=\tilde{a}\left(\left|v-v_{*}\right|\right), \gamma:=\tilde{\gamma}\left(\left|v-v_{*}\right|\right)$ (Cf. [Mat06] and [DMar]).

Our proposition consists in introducing the simplified model (16) - (30), where $a$ and $\gamma$ (appearing in formulas $(21)-(25))$ are replaced by $\tilde{a}(\sqrt{6 T})$ and $\tilde{\gamma}(\sqrt{6 T})$ respectively [that is, $\left|v-v_{*}\right|$ is replaced by its mean quadratic value, as in formula (64)].

## 4. Numerical simulations

4.1. Numerical method. In order to solve (16) - (30), we use a particle method (with constant weight $w$ ): the density $f$ is discretized as

$$
f(n \Delta t, v, e) \sim \sum_{i=1}^{N} w \delta_{v_{i}(n \Delta t), e_{i}(n \Delta t)}
$$

The "Vlasov-Fokker-Planck" part of eq.(16) [that is, the l.h.s. of the equation] is solved by discretizing (at the first order) the characteristic ODEs for $v_{i}$ and $e_{i}$. Moreover, a realization of the Brownian motion is used for the term proportional to $\partial_{e}^{2} f$. The exact conservation of the momentum and total energy is enforced at the end of this procedure. The "BGK" part of eq. (16) [that is, the r.h.s. of the equation] is treated by modifying the velocities of a randomly chosen set of particles (Monte-Carlo method). Once again, the conservation of momentum and kinetic energy (which implies total energy too since the internal energy remains unchanged in that step) is enforced at the end of the time step.

Note also that the numerical results obtained with this discretization of eq. (16) - (30) are compared with simulations of the original equation (31) obtained thanks to a DSMC scheme (the code is a modified version of the code used in [Bar04, DMar])
4.2. Numerical experiments; Maxwell molecules. This subsection is dedicated to the study of the behavior of solutions of eq. (16) - (30) in the case of Maxwell molecules. Since the evolution of some moments of the original eq. (31) is explicitly known for this cross section (in particular the evolution of $T_{i j}$ ), it is possible to make comparisons with this explicit formula. When no such explicit formula exists, we use instead a comparison with solutions of eq. (31) obtained numerically.

We start with the study of the evolution of the directional temperatures $T_{i j}$ for an anisotropic initial distribution. We provide Fig. 6 for $T_{12}$ when $\gamma=0.3$. We compare in this figure the values of $T_{12}$ obtained by the discretization of the original Boltzmann eq. (31) and those obtained by the discretization of our simplified eq. (16) - (30). The same is performed in Fig. 7 for $T_{11}, T_{22}$ when $\gamma=0.6$. The trend to equilibrium of directional temperatures can be observed during a short transient phase.

As expected, the curves are extremely close, since the $T_{i j}$ satisfy in both models the same ode [the coefficients in eq. (16) have been built for that purpose]. This test in fact shows that the error
of dicretization for eq. (16) as well as eq. (31) is negligeable. We have added on the figures the curve corresponding to the exact solution of the ode satisfied by $T_{12}, T_{11}, T_{22}$.

We then turn to the evolution of the parameter $g$. We provide figures (Cf. Fig. 13) which show a comparison of the case when $f$ is the (discretized) solution of the Boltzmann equation (31) with the case when $f$ is the (discretized) solution of the simplified model (16). The different figures correspond to different choices of parameters (of inelasticity) $\gamma$ and (of exchange of energy) $a$.

As can be seen on the figures, the curves for the two models are very close, except in the special (and non-physical) case when $a=0$ (that is, when internal energy is not exchanged at all during the collisions). The fact that $g$ behaves in the same way for the two models is no surprise since the parameters of the simplified model are built for that purpose. It was however not completely obvious that this behavior would be so close (still except when $a=0$ ), since $g$ does not exactly satisfy any ode (as $T_{i j}$ did): remember that the computations leading to the parameters in the simplified model were only approximations.

Next curves concern moments which have not been used for specifying the parameters of the simplified model (16), namely $\left|e-e_{\text {avr }}\right|$ (Cf. Fig. 14), and $\frac{\left|v_{2}\right|}{\sqrt{T(t)}+\left|v_{1}\right|}$ (Cf. Fig. 15).

As could be guessed, the curve coming out of eq. (31) and those coming out of the simplified model (16) do not fit as well as the curves for $T_{i j}$ or even $g$. The gap between them however remains reasonable.
4.3. Numerical experiments; hard spheres. We provide in this subsection computations for the same quantities as in the previous subsection, but in the case when the cross section is that of hard spheres (which is much more physically relevant). In this situation, even quantities like $T_{i j}$ are not exactly solutions of an ode, so that it is only possible to compare the numerical experiments for the two models.

As in the previous subsection, we start with the evolution of the directional temperatures $T_{i j}$, for an anisotropic initial distribution. The fit between the curves for models (31) and (16) is of course not as perfect as in the case of Maxwell molecules, but it still remains quite satisfactory (Cf. Fig. 16).

The same experiment is done for the directional temperature $T_{i i}$ when $\gamma=0.6$ (Fig. 17)
The same can be said of the evolution of $g$ (Cf. Fig. 23), notice that the case when $a=0$ still remains the worst.

We use a logarithmic scale in order to check that the slope of the decay of $g$ (when the time is large) is respected in the simplified model. This can be seen in Fig. 26 (we consider the elastic case $\gamma=1$ so that an exponential behaviour is expected for $g(t)$, as can be guessed from (65)).

We conclude this subsection by presenting curves for the moments $\left|e-e_{a v r}\right|$ (Cf. Fig. 27), and $\frac{\left|v_{1}\right|}{\sqrt{T(t)}+\left|v_{2}\right|}$ (Cf. Fig. 28).

We observe (as expected) a slight degradation of the results w.r.t. the case of Maxwell molecules.

### 4.4. Numerical experiments; velocity-depending parameters.

This subsection is devoted to the presentation of results when both $\gamma$ and $a$ are functions of $\left|v-v_{*}\right|$ in eq. (31), as described in subsection 3.4.
More precisely, we consider the following formulas for the parameters $\gamma$ and $a$ (Cf. [Mat06] and [DMar]):

$$
\begin{equation*}
\tilde{\gamma}\left(\left|v-v_{*}\right|\right)=\exp \left(-\frac{\gamma_{1}}{|v-v *|}\right), \tag{99}
\end{equation*}
$$

$$
\begin{equation*}
\tilde{a}\left(\left|v-v_{*}\right|\right)=1-\exp \left(-\frac{a_{1}}{|v-v *|}\right) \tag{100}
\end{equation*}
$$

We compare the results obtained on one hand by using the original Boltzmann equation (with $a:=\tilde{a}\left(\left|v-v_{*}\right|\right)$ and $\gamma:=\tilde{\gamma}\left(\left|v-v_{*}\right|\right)$ given by (99), (100); and with hard spheres), and on the other hand by using our simplified model with $a:=\tilde{a}(\sqrt{6 T}), \gamma:=\tilde{\gamma}(\sqrt{6 T})$, as proposed in subsection 3.4.

We first compare the evolution of the directional temperatures $T_{12}(t), T_{11}(t), T_{22}(t)$, in order to observe the trend to equilibrium of those temperatures (Fig. 31). We take two different values for the parameter $\gamma_{1}$ in $\tilde{\gamma}$.

On a longer time scale, we also present results in LogLog scale (Fig. 37) for the evolution of the temperature $T$ (that is, we check Haff's law numerically).

We end up this series of simulation by one example of evolution of the variance of internal energy $g(t)$ (Fig. 38).

In our simulations, no sensible degradation was observed w.r.t. the case of hard spheres (with given $a, \gamma)$.

## 5. Conclusion

We introduced in this paper a model of BGK type for the description of the effect of collisions which are inelastic and in which the internal energy of the particles (droplets) is tracked (and can be exchanged during collisions).

This model can be obtained almost entirely in a rational way when the collisions occur with a cross section of Maxwell molecules type.

In the more realistic case of hard spheres (and even more when the inelasticity and internal energy exchange parameters can depend on the relative velocity of incoming droplets), approximations must be performed.

The quality of these approximations were tested at the numerical level.

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Figure 1. Evolution of $T_{11}(t)$ and $T_{33}(t)$. The upper curve corresponds to $T_{33}(t)$. The simulation is performed on the typical time of equilibrium of directional temperatures (which is much shorter than the time of decay due to the inelastic behavior). The approximation with the anisotropic Gaussian (26) fits best with the evolution of the solution of the Boltzmann equation.


Figure 2. Evolution of the temperature $T(t)$ in the same conditions, but on a longer time scale. We see that on this time scale, the isotropic approximation $\sqrt{\frac{15}{9}} \sqrt{6 T}$ works as well as formula (26).

Figure 3. Initial datum corresponding to $T_{33}=4 T_{11}$. The inelasticity parameter is $\gamma=0.6$, different approximations of the cross section are performed.


Figure 4. Evolution of $g(t)$ with $\gamma=1, a=0.5$. Hard Spheres. The formula (27) fits best with the original Boltzmann model.


Figure 5. Evolution of $g(t)$ with $a=0, \gamma=0.6$. Hard Spheres.


Figure 6. Evolution of $T_{12}(t)$ with $\gamma=0.3$. Maxwell molecules.


Figure 7. Evolution of $T_{11}(t), T_{12}(t)$ with $\gamma=0.6$. Maxwell molecules.


Figure 8. $a=0, \gamma=0.6$.


Figure 10. $a=0.5, \gamma=0.6$.


Figure 9. $a=1, \gamma=0.6$.


Figure 11. $a=1, \gamma=1$.


Figure 12. $a=0.5, \gamma=1$.
Figure 13. Evolution of $\mathrm{g}(\mathrm{t})$. Maxwell molecules.


Figure 14. Evolution of $q_{1}(t)=\frac{\int f(t)\left|e-e_{\text {avr }}\right| d v d e}{\int f(t) d v d e}$ with $a=1, \gamma=0.6$. Maxwell molecules.


Figure 15. Evolution of $q_{2}(t)=\int_{v} \int_{e} f(t) \frac{\left|v_{2}\right|}{\sqrt{T(t)}+\left|v_{1}\right|} d v d e$ with $\gamma=0.3$. Maxwell molecules.


Figure 16. Evolution of $T_{12}(t)$ with $\gamma=0.3$. Hard spheres.


Figure 17. Evolution of $T_{11}(t), T_{22}(t)$ with $\gamma=0.6$. Hard Spheres.


Figure 18. $a=0, \gamma=0.6$.


Figure 20. $a=1, \gamma=0.6$.


Figure 19. $a=0.5, \gamma=0.6$.


Figure 21. $a=0.5, \gamma=1$.


Figure 22. $a=1, \gamma=1$.
Figure 23. Evolution of $g(t)$. Hard spheres.


Figure 24. $a=0.5, \gamma=1$


Figure 25. $a=1, \gamma=1$

Figure 26. Evolution of $g(t)$. Hard spheres. Semilog scale.


Figure 27. Evolution of $q_{1}(t)=\frac{\int_{v} \int_{e} f(t)\left|e-e_{\text {avv }}\right| d v d e}{\int_{v} \int_{e} f(t) d v d e}, a=1, \gamma=0.6$. Hard Spheres.


Figure 28. Evolution of $q_{3}(t)=\int f(t) \frac{\left|v_{1}\right|}{\sqrt{T(t)}+\left|v_{2}\right|} d v d e, \gamma=0.6$. Hard spheres.


Figure 29. $\gamma_{1}=160$


Figure 30. $\gamma_{1}=1600$

Figure 31. Evolution of $T_{12}(t) . \gamma$ depending on $\left|v-v_{*}\right|$.


Figure 32. $\gamma_{1}=160$


Figure 33. $\gamma_{1}=1600$

Figure 34. Evolution of $T_{11}(t), T_{22}(t) . \gamma$ depending on $\left|v-v_{*}\right|$.


Figure 35. $\gamma_{1}=160$


Figure 36. $\gamma_{1}=1600$.

Figure 37. Evolution of $T(t) . \gamma$ depending on $\left|v-v_{*}\right|$. Log Log scale


Figure 38. Evolution of $g(t) . \gamma_{1}=160 . a_{1}=6000 . \gamma, a$ depending on $\left|v-v_{*}\right|$.

